

San José State University

Math 253: Mathematical Methods for Data Visualization

Isometric Feature Mapping (ISOmap)

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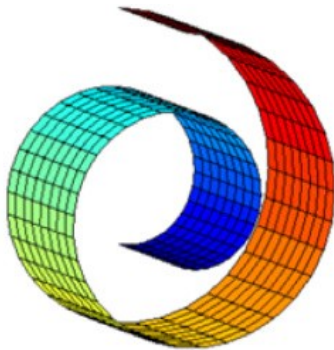
ISOMap

Briefly, **ISOMap** is MDS combined with a special metric, called **geodesic distance**, for reducing the dimensionality of data sampled from a smooth manifold:

- **Paper:** *A Global Geometric Framework for Nonlinear Dimensionality Reduction*, J. B. Tenenbaum, V. de Silva and J. C. Langford, *Science* 290 (5500): 2319–2323, December 2000
- **Website:** <https://web.mit.edu/cocosci/isomap/isomap.html>



(a)



(b)

Motivation

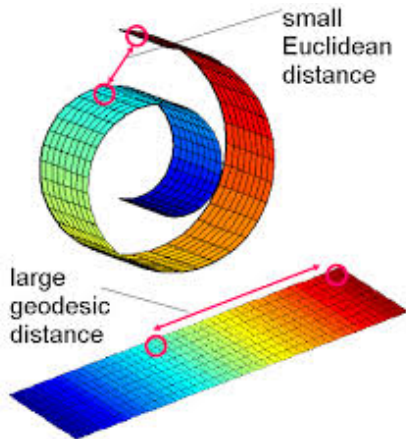
Consider applying PCA to the Swissroll data. There are the following drawbacks:

- The PCA dimension needs to be higher, and sometimes much higher, than the manifold dimension (otherwise PCA may project faraway points along the manifold to nearby locations);
- PCA cannot capture the curved dimensions (its principal directions are generally not meaningful).

The ISOmap approach to dimension reduction

Instead of preserving the Euclidean distance, we will apply MDS to preserve the **geodesic distance**, which

- captures the true, nonlinear geometry corresponding to the curved dimension
- allows to see the transitioning along the manifold (and thus the global structure).

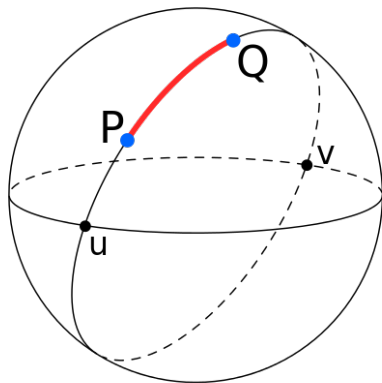


How to find geodesic distances

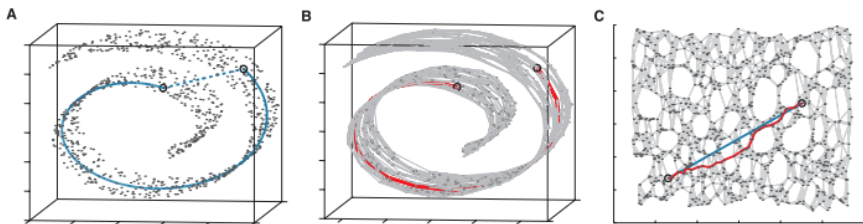
The geodesic distance of two data points that live in a manifold is the shortest distance along the manifold.

On a sphere, it is just the great-circle distance.

The exact geodesic distances are often impossible to find (unless we know the true manifold).



In practical settings where we are only given a data set X sampled from an unknown manifold \mathcal{M} , we can approximate the true geodesic distances $d_{\mathcal{M}}(i, j)$ by the shortest-path distances $d_G(i, j)$ on a nearest-neighbor graph G built on the data set.



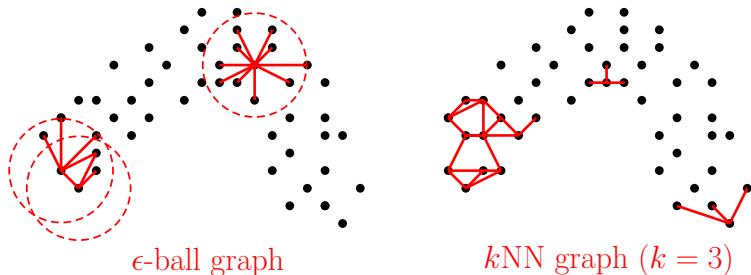
Detailed steps:

1. Build a neighborhood graph G from the given data by connecting only “nearby points” with edges weighted by their Euclidean distances, i.e.,

$$d_X(i, j) = \|\mathbf{x}_i - \mathbf{x}_j\| \quad \text{if } \mathbf{x}_i, \mathbf{x}_j \text{ are “close” (and 0 otherwise)}$$

where “closeness” is defined in one of the following ways:

- **ϵ -ball approach:** For each \mathbf{x}_i , another point \mathbf{x}_j is close if and only if $\|\mathbf{x}_i - \mathbf{x}_j\| \leq \epsilon$, or
- **k NN approach:** For each point \mathbf{x}_i , \mathbf{x}_j is close if it is among the the k nearest neighbors of \mathbf{x}_i .



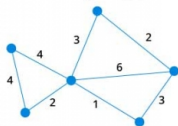
2. Apply Dijkstra's algorithm¹ with the nearest neighbor graph G (constructed by either method) to find the shortest-path distances for all pairs of data points ($d_G(i, j)$).

¹https://upload.wikimedia.org/wikipedia/commons/5/57/Dijkstra_Animation.gif

ISOmap

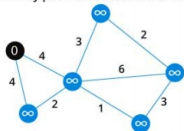
1

Start with a weighted graph



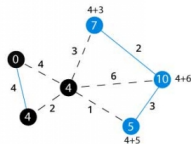
2

Choose a starting vertex and assign infinity path values to all other vertices



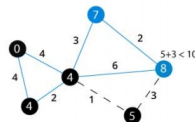
5

Avoid updating path lengths of already visited vertices



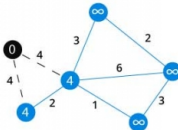
6

After each iteration, we pick the unvisited vertex with least path length. So we chose 5 before 7



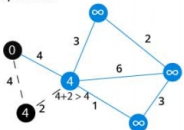
3

Go to each vertex adjacent to this vertex and update its path length



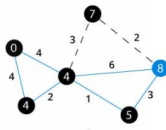
4

If the path length of adjacent vertex is lesser than new path length, don't update it.



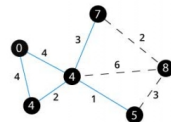
7

Notice how the rightmost vertex has its path length updated twice



8

Repeat until all the vertices have been visited



(Source: <https://www.programiz.com/dsa/dijkstra-algorithm>)

The ISOmap algorithm

Input: Pairwise distances $d_X(i, j)$ of data points in the input space, embedding dimension $k \geq 1$, neighborhood graph method (ϵ -ball or k NN)

Output: A k -dimensional representation of the data $\mathbf{Y} \in \mathbb{R}^{n \times k}$.

1. Construct a neighborhood graph G from the given distances $d_X(i, j)$ using the specified method
2. Compute the shortest-path distances $d_G(i, j)$ between all vertices of G by using Dijkstra's algorithm.
3. Apply MDS with $d_G(i, j)$ as input distances to find a k -dimensional representation \mathbf{Y} of the original data

Implementations

MATLAB:

- Code by the ISomap authors:
<https://web.mit.edu/cocosci/isomap/isomap.html>
- Matlab Toolbox for Dimensionality Reduction by van der Maaten:
<https://lvdmaaten.github.io/drtoolbox/>
- MANI: Manifold Learning Toolkit (by T. Wittman):
<http://macs.citadel.edu/wittman/Research/Mani/mani.m>

Python: <https://scikit-learn.org/stable/modules/generated/sklearn.manifold.Isomap.html>

Demonstration

See

https://www.cs.cmu.edu/~bapoczos/Classes/ML10715_2015Fall/slides/ManifoldLearning.pdf

Summary

We presented the MDS method for dimensionality reduction which aims to preserve certain kind of distances of the data:

Special cases:

- Euclidean distance: PCA
- Geodesic distance: ISOmap